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SCIENTIFIC REPORT No. 7

THE INITIAL ROLL-UP OF A THICK, TWO-DIMENSIONAL WAKE BEHIND A WING OF FINITE SPAN

BY

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ACCORD OF THE CONTROL OF

Department of Aeronautical Engineering
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Haifa, Israel

T.A.E. REPORT No. 262

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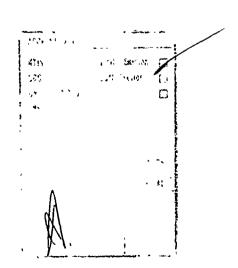
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THE INITIAL ROLL-UP OF A THICK, TWO-DIMENSIONAL WAKE BEHIND A WING OF FINITE SPAN.

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TAE REPORT No. 262



ABSTRACT

Previous investigations of wing-wake roll-up have assumed the wake to be a vortex sheet of zero thickness. This immediately leads to the conclusion that, as soon as the process starts, a spiral of near axisymmetric form, with an infinite number of turns, forms at the edge, as predicted by the work of Kaden, which must apply to the early stages of roll-up for any sheet of zero thickness. In addition, most investigators, starting with Westwater, have replaced the continuous vortex sheet by discrete vortex lines.

In this report, the aforementioned unrealistic features are removed by assuming that the wake cross-section has a finite thickness and some plausible shape. A two-dimensional method, analogous to that of Westwater, is developed, assuming that the wake cross-section contains vorticity in an otherwise irrotational field. The wake is divided into triangular elements and the vorticity in these is determined by assuming a linear transverse velocity profile in the wake and that the initial, unrolled wake moves downwards as determined by the wing spanwise loading through ordinary wing-wake theory. Euler time-step integration is then used to calculate the wake development under its own induced velocity field, ignoring viscous dissipation.

Three examples of the initial stages of roll-up, for elliptic wakes of thickness ratios .04, .05 and .06, are calculated. A finite spiral structure is observed to develop and, within the range covered, the thickness only seems to affect the number of turns in the spiral, other parameters seeming to be almost unaffected.

Plans for continuation of the work are discussed.

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LIST OF SIMBOLS

- A wake cross-section at any station x.
- A' initial wake cross-section at x = 0.
- AR aspect ratio of wing.
- a side of triangular element, opposite corner A, divided by s.
- b side of triangular element, opposite corner B, divided by s.
- C boundary of cross-section A.
- C' boundary of cross-section A'.
- C, wing lift coefficient.
- c side of triangular element, opposite corner C, divided by s.
- $K_n = \xi_n^* \Delta A_n^*$.
- M total number of triangular elements in wake cross-section.
- N number of different values of ξ_n^* .
- n number denoting a typical triangular element.
- P perimeter of S.
- $r_A = |\zeta \zeta_A|/s.$
- $r_B = |\zeta \zeta_B|/s.$
- $r_c = |\zeta \zeta_c|/s$.
- S closed region with constant vorticity distribution.
- s wing semi-span.
- t dimensionless time. See Equation (4).
- U free stream velocity.
- V element influence function. See Equation (14).
- v velocity component in the y direction.
- v non-dimensional form of v. See Equation (3).

```
element influence function. See Equation (15).
             velocity component in the z direction.
             non-dimensional form of w. See Equation (3).
             - \mathbf{w}_{_{\mathbf{T}}}^{\star} is the usual downwash calculated in the Treffz plane
             for an unrolled wake.
             streamwise coordinate.
             spanwise coordinate positive to the right.
У
            = y/s.
            third coordinate of the right-handed set x, y, z.
            = z/s.
            = arg (\zeta - \zeta_n).
            = arg (\zeta_B - \zeta_A) .
            = arg (\zeta_C - \zeta_A) .
           = arg (\zeta - \zeta_B).
β
            = arg (\zeta_A - \zeta_B).
           = arg (\zeta_C - \zeta_B).
            = arg (\zeta - \zeta_C).
Υ
            = arg (\zeta_A - \zeta_C).
            = arg (\zeta_B - \zeta_C).
            area of ntn triangular element.
            = \Delta A_n/s^2.
ΔA'n
Δt*
            dimensionless time step in numerical integration.
            contribution to v from nth triangular element.
            contribution to w from nth triangular element.
```

```
thickness ratio of elliptic wake cross-section.
            = y + iz.
            \zeta at corner A of nth element.
           ζ at corner B of nth element.
            ζ at corner C of nth element.
            = ccs<sup>-1</sup>y .
            = \tan^{-1}(dz^*/dy^*)_{C'}
 \xi(z,y,z) vorticity distribution within A •
\xi^*(t^*,y^*,z^*) non-dimensional form of \xi. See Equation (5).
            constant value of \xi in nth triangle.
           non-dimensional form of \xi_n.
           constant value of \xi inside S.
ω(y)
           vorticity distribution within A'.
ω*(y*)
            non-dimensional form of \ \omega \text{.} See Equation (5).
```

1. INTRODUCTION

Many investigators have studied the rolling-up of the vortex wake behind a wing of finite span. The earliest step in this study was the work of Kaden (1) who found an analytical solution for the rolling-up with time of a semi-infinite, straight, two-dimensional vortex sheet. This solution must represent the situation very close to the edges of a finite-span vortex sheet of zero thickness, in two or three dimensions, during the initial stage of the rolling-up process. An important result following from Kaden's work is that, from the very onset of rolling-up, due to the infinite velocity at the sheet edge, a spiral of near-axi-symmetric form, with an infinite number of turns, is established at the edge. This is a consequence of the assumption of zero thickness for the sheet.

Westwater (2) considered a finite-span, zero-thickness wake resulting from an elliptically-loaded wing and assumed that the roll-up could be treated as a two-dimensional time-dependent process, where the configurations at successive stages in time represent successively further downstream sections of the wake, as fixed by the forward speed of the wing multiplied by the time. This approach is evidently suitable for wakes which roll up relatively slowly far behind the wing, such as are found with high-aspect ratio, unswept wings. Westwater further simplified his calculations by replacing the continuous vortex sheet by a row of infinite line vortices. Clements and Maull (3) have recently used this technique for non-elliptic span-loadings. Westwater's method is subject

to certain numerical difficulties which have been the subject of a number of investigations. A particularly careful recent review and study of this matter is due to Moore (4), who develops a method for overcoming the problem.

The line-vortex method has been extended to cover three-dimensional effects, such as those of bound vorticity and the finite origin and streamwise curvature of the trailing vortices, by the use of the vortex-lattice procedure (5,6,7,8,9). This leads to results applicable to low-aspectratio and swept wings.

The present work is an attempt to remove the unrealistic features of the earlier models, namely zero wake thickness and vorticity concentrated on lines, by assuming that the wake vorticity is contained in a layer of finite thickness with some plausible cross-sectional shape. The wake flow is assumed to be two-dimensional and the rolling- up is studied via the time-dependent development of this model, exactly as in Westwater's work, so that we deal with a slow rolling-up taking place far behind the wing, once more. The introduction of vorticity distributed continuously throughout the wake cross-section enables us to obtain a more acceptable picture of the initial rolling up phase than the infinite spiral of Kaden.

Having selected an appropriate wake cross-section its area is divided into triangular elements within each of which the vorticity is assumed constant, and for which simple expressions giving the velocity field have been derived (see Section 3). The strength of the vorticity within each

triangle is determined using two assumptions:

- (1) The vorticity is constant through the wake thickness. This corresponds to an assumption that the transverse velocity profile within the wake is linear.
- (2) The periphery of the wake is moving downwards with a velocity determined by spanwise position and wing spanwise loading, exactly as in ordinary wing-wake theory.

Assumption (1) can evidently be removed at the cost of increasing the number of triangular elements used.

Once the triangle strengths are found, the network of points defining the wake is allowed to distort with time under its self-induced velocity field, using Euler integration. During this process viscous dissipation is neglected, so that the vorticity inside each triangle remains constant, as will its area (due to continuity), even though the shape changes.

Examples of the initial roll-up phase have been calculated for three wakes of different thicknesses and elliptic cross-sections, subjected to uniform downwash (corresponding to elliptic spanwise loading). Details and results are given in Sections 5 and 6, and plans for future work in Section 7.

2. THE MATHEMATICAL MODEL

The mathematical model of the wake and the notation are illustrated in Fig. 1.

The unrolled wake cross-section A', whose boundary is denoted by C', stretches between y = -s and y = +s in the plane x = C. At subsequent stations x = x, the boundary is denoted by C and the wake has a rolled up form of cross section A with vorticity distribution $\xi(x,y,z)$ determined by the original configuration of the wake cross-section, the original vorticity distribution within it, $\xi(0,y,z)$, and the elapsed time x/U. It is assumed that

$$\xi(0,y,z) = \omega(y) \qquad (1)$$

corresponding to a linear variation with z of the velocity, v, within the initial wake section, if the wake is assumed thin.

We define dimensionless coordinates

$$y^* = \frac{y}{s} \; ; \; z^* = \frac{z}{s}$$
 (2)

and since a typical velocity of the flow in the wake cross-sectional plane is $\frac{2UC_L}{\pi . AR}$, we also define dimensionless velocity components, time and vorticity by

$$v^* = \frac{\pi AR. v}{2UC_L}; \quad w = \frac{\pi AR. w}{2UC_L},$$
 (3)

$$t^* = \frac{2C_L x}{\pi . AR.s} , \qquad (4)$$

$$\omega^{*}(y^{*}) = \frac{\omega \pi.AR.s}{2UC_{L}} ; \xi^{*}(t^{*},y^{*},z^{*}) = \frac{\xi\pi.AR.s}{2UC_{L}} .$$
 (5)

We assume that ω or ω^* is determined by the boundary conditions:

(a)
$$w^* \cos \lambda - v^* \sin \lambda = w_{\overline{1}}^* (y^*) \cos \lambda$$
 (6)

on C'

where
$$(dz^*/dy^*)_{C'} = tan\lambda$$
, and
(b) $v^{*2} + v^{*2} \rightarrow 0$ as $v^{*2} + v^{*2} \rightarrow \infty$. (7)

 $-w_{\underline{I}}^{*}(y^{*})$ is the non-dimensionalised downwash distribution in the Treffz plane as calculated from the usual unrolled thin-wake theory. For example, $w_{\underline{I}}^{*} = -1$ for elliptic spanwise load distribution. It is readily shown that, in the general form, $w_{\underline{I}}^{*}$ is dependent on the form of the spanwise loading and y^{*} only (c.f. reference 3).

It now follows that for a given initial wake cross-section and spanwise loading, the velocities \mathbf{v}^{\star} and \mathbf{w}^{\star} of a given fluid particle are functions of \mathbf{t}^{\star} only, so that the subsequent non-dimensional coordinates of the particles constituting the rolled wake are functions of \mathbf{t}^{\star} only, determined by the differential equations

$$\frac{dy^*}{dt^*} = v^* \quad ; \quad \frac{dz^*}{dt^*} = v^* \quad . \tag{8}$$

The equations (8) are integrated numerically step by step, starting from the initial configuration, using Euler integration.

It remains to determine the velocity field (v * , w *) due to the distribution ξ^{\star} within C.

3. THE VELOCITY FIELD

At any value of x, the two-dimensional velocity field, (v, w), is determined by integrating the effects of point vortices of strengths $\xi(x,y,z)dy dz$ over the area of the wake cross-section, A.

To facilitate the numerical calculations, A is divided into a finite number of small triangular elements within each of which the value of ξ is assumed constant. We now find expressions for Δv_n^* and Δw_n^* due to a typical element of this kind for points outside its boundary, or approaching the boundary in a limiting sense. This enables us to calculate v^* and w^* for the assemblage of triangles at all the node points of the triangular mesh, including internal nodes of A, since such points may be regarded as being inside infinitesimal cavities excluded from all the adjacent triangles, and we calculate, in effect, the principal value of the velocity integral – which is precisely the required definition of this integral inside the vorticity distribution.

The velocity field outside any area S containing a constant vorticity distribution, $\boldsymbol{\xi}_{\text{S}}$,may be written

$$v - iw = \frac{-i\xi_s}{2\pi} \int_{S} \frac{dy_1 dz_1}{y + iz - y_1 - iz_1} \qquad (9)$$

Using Green's theorem, this may be converted to a line integral around P, the perimeter of S:

$$v - iw = \frac{i\xi_s}{2\pi} \int_{p} \ln(\zeta - y_1 - iz_1) dy_1$$
 (10)

If (10) is applied to a typical triangle of A ,of area ΔA_n , vorticity distribution strength ξ_n and vertices defined by ζ_A , ζ_B , ζ_C (Fig. 2), we obtain

$$\Delta v_{n} - i\Delta w_{n} = -\frac{-i\xi_{n}\Delta A_{n}}{\pi} \left\{ \frac{\zeta - \zeta_{A}}{(\zeta_{C} - \zeta_{A})(\zeta_{B} - \zeta_{A})} \ln(\zeta - \zeta_{A}) + \frac{\zeta - \zeta_{C}}{(\zeta_{C} - \zeta_{B})(\zeta_{A} - \zeta_{B})} \ln(\zeta - \zeta_{C}) + \frac{\zeta - \zeta_{C}}{(\zeta_{A} - \zeta_{C})(\zeta_{B} - \zeta_{C})} \ln(\zeta - \zeta_{C}) \right\}.$$
(11)

 ξ_n and ΔA_n are both invariant with the motion for an infinitesimal triangle in incompressible flow, the product $\xi_n \Delta A_n$ being the circulation around the element.

If we now write
$$s^2 \Delta A_n^* = \Delta A_n$$
, then
$$\xi_n \Delta A_n = \frac{2UsC_L}{\pi AR} \xi_n^* \Delta A_n^* = \frac{2UsC_L}{\pi AR} K_n$$
(12)

and if (see Fig. 2)

$$\zeta - \zeta_{A} = \operatorname{sr}_{A} e^{i\alpha} ; \quad \zeta - \zeta_{B} = \operatorname{sr}_{B} e^{i\beta} ; \quad \zeta - \zeta_{C} = \operatorname{sr}_{C} e^{i\gamma}$$

$$\zeta_{B} - \zeta_{A} = \operatorname{sc} e^{i\alpha_{B}} ; \quad \zeta_{C} - \zeta_{A} = \operatorname{sbe}^{i\alpha_{C}}$$

$$\zeta_{C} - \zeta_{B} = \operatorname{sae}^{i\beta_{C}} ; \quad \zeta_{A} - \zeta_{B} = \operatorname{sce}^{i\beta_{A}}$$

$$\zeta_{A} - \zeta_{C} = \operatorname{sbe}^{i\gamma_{A}} ; \quad \zeta_{B} - \zeta_{C}$$
(13)

we obtain from (11)

$$\Delta v_{n}^{\star} = \frac{K_{n}}{\pi} \left\{ \frac{r_{A}}{bc} \left[\sin(\alpha - \alpha_{C} - \alpha_{B}) \ln r_{A} + \alpha \cos(\alpha - \alpha_{C} - \alpha_{B}) \right] + \frac{r_{B}}{ca} \left[\sin(\beta - \beta_{C} - \beta_{A}) \ln r_{B} + \beta \cos(\beta - \beta_{C} - \beta_{A}) \right] + \frac{r_{C}}{ab} \left[\sin(\gamma - \gamma_{A} - \gamma_{B}) \ln r_{C} + \gamma \cos(\gamma - \gamma_{A} - \gamma_{B}) \right] \right\}$$

$$= K_{n} V_{n} (\gamma^{\star}, z^{\star})$$
(14)

$$\Delta w_{n}^{*} = \frac{K_{n} \{r_{A} \}}{\pi} \{\cos(\alpha - \alpha_{C} - \alpha_{B}) \ln r_{A} - \sin(\alpha - \alpha_{C} - \alpha_{B})\} +$$

$$+ \frac{r_{B} \{\cos(\beta - \beta_{C} - \beta_{A}) \ln r_{B} - \beta \sin(\beta - \beta_{C} - \beta_{A})\} +$$

$$+ \frac{r_{C} \{\cos(\gamma - \gamma_{A} - \gamma_{B}) \ln r_{C} - \gamma \sin(\gamma - \gamma_{A} - \gamma_{B})\} +$$

$$= K_{n} W_{n} (y^{*}, z^{*}) \qquad (15)$$

Hence we have the approximations

$$v^* \stackrel{N}{\sim} \sum_{n=1}^{M} K_n V_n (y^*, z^*)$$
(16)

$$w^{*} \stackrel{\wedge}{\sim} \sum_{n=1}^{M} K_{n} w_{n} (\underline{y}^{*}, z^{*}) \qquad (17)$$

4. THE NUMERICAL PROCEDURE

Because of the spanwise symmetry of the initial cross-section, A', and the assumption (1), the M values of K_n are dependent on a smaller number of values of ξ_n^* , say N. The boundary condition (6) is now applied at N suitable node points on the initial boundary A' (excluding the tip points), using the expressions (16) and (17), with unknown coefficients, $K_n = \xi_n^* A_n^*$, thus yielding N linear equations for the ξ_n^* and hence the K_n . The equations (16) and (17) may now be used to evaluate v^* and v^* at all values of v^* , once the dimensionless coordinates of the triangles are known. These are found step by step by numerical integration of the equations (8) forward in time v^* , starting with the known initial set of triangles within A'. The development of the wake roll-up is thus calculated step by step. The v^* coordinate of the "centroid" of vorticity of one half of the wake is calculated at each step. This should remain constant v^* 0 and provides an accuracy check.

5. THE WAKE OF ELLIPTIC CROSS-SECTION SUBJECT TO UNIFORM DOWNVASH

In this case the equation of C' is

$$z^* = z \in \sqrt{1 - y^{*2}}$$
 (18)

and

$$w_{\tau}^{\star} = -1$$
 . (19)

Also

$$\tan \lambda = \mp \frac{\varepsilon y^*}{\sqrt{1 - y^{*2}}} . \tag{20}$$

The cross-section A' is divided into triangular elements as shown in Figure 3. It was found necessary to concentrate the triangles near the tips. This was done as follows. Firstly a basic set of spanwise stations was established by using an even number of equal divisions of the eccentric angle coordinate

$$\theta = \cos^{-1} y^* \tag{21}$$

across the span. Next, the segment at the tip was further subdivided into two equal θ intervals and all resulting divisions were then again subdivided into two for a specified number of the segments, starting from the tips and moving inboard. Using the horizontal diameter of the ellipse as another division line, triangles may then be filled in as shown in Figure 3. ξ_n^* is taken as constant over the four triangles lying between any two vertical lines (at the tip - over two triangles) and the same value is taken for the symmetrically placed group on the other half wake. In the illustration, the spanwise subdivision is 8+2+6, the number of triangles is 60 and the number of different values of ξ_n^* is 8. The points for applying the

boundary condition are shown circled.

An analytic solution exists for the downward moving elliptic cylinder, which corresponds to the flow at $t^*=0$. The flow calculated by the present method at $t^*=0$ was compared t^* his for the three cases considered, namely, $\epsilon=.04$, .05 and .06. In all these cases, a subdivision of 40+2+8 spanwise gave results for surface velocity, total amount of vorticity in one half wake and spanwise position of centroid, which were considered to compare adequately with the theoretical values and this distribution of points was also found to be just adequate for describing the spiral structure of the core up to the time reached in the calculation of the roll-up. During the roll-up, the centroid position spanwise remained constant to a high degree of accuracy for the range covered (change not more than 1 part in 780). The total times covered were $t^*=.0128$, .0160 and .0192 for the thickness ratios .04, .05 and .06, respectively.

The appearance of the tip region is shown for various stages of this initial roll-up in Figures 4,5, and 6 for ε = .04, .05 and .06, respectively and in Figure 7 one example of a complete half-wake is shown. It should be noted that to clarify the inner detail of the spiral, the vertical scale has been exaggerated in these figures and this vertical scale is not uniform throughout all the pictures. The results are discussed in the next Section.

6. DISCUSSION AND RESULTS

The time step, Δt , used in the numerical integration was found to be a critical parameter in the calculation, whereas the results were not very sensitive to spanwise divisions, provided sufficient were present near the tip to ensure enough points, at close enough spacings, to describe the spiral structure. After some experiment, it was found that the 40 + 2 + 8 subdivision gave results as good as those from larger numbers of cells, although the need for further points near the tip does not become evident at later stages in the spiral development.

As regards Δt^* , if this is taken very small, chaotic motion of the points can develop after a large number of small steps have been taken during the initial short period of high distortion rate of the wake tip. This effect, which is not so critical later on in the calculation, appears to be due to accumulated errors resulting from neglect of the distortions of the triangular elements at each step, distortions which makes them increasingly curvilinear in reality. On the other hand, too large a Δt^* leads to incorrect wake shapes which are not substantiated on reduction of the time step. There seems to be an optimum Δt^* for each thickness ratio which avoids chaotic motion and for which the wake shape is relatively invariant with modest changes of this time step.

Another difficulty which occurred was overlap of triangular elements (an event formally violating the equation of continuity of the motion). This occurred either near the beginning of the roll-up, when the spiral tip, turning inwards, occasionally crossed onto the main body of the

wake, or, later on, within the turns of the spiral. In the former case a cure could be effected by slightly decreasing Δt , and in the latter case more points should be incorporated near the tip. However, it was found impossible to increase the number of points sufficiently to completely remove overlap within the spiral during the later stages when the spiral coils stretch and wind up tightly. This is evidently a difficulty inherent in the use of straight-sided elements to represent a stretching spiral structure. It was found, however, that the shape of smooth spiral curves drawn through the node points was not greatly affected by the increase of points to avoid overlap, so it was concluded that the true, smooth spiral shape was still given fairly accurately by the node points even when a small amount of overlap occurred, provided that the pattern formed a logical extension of previous non-overlapping cases and that there was consistency between neighbouring lines of the coil, that is between the original center-line, which is shown dotted in the drawings, and the outer boundaries.

Using this approach, we are able to follow the up to one and threequarter turns of the spiral, which occur in the present examples.

An analysis of the results shows that, for the range of thickness ratios covered, for the elliptic cross-sectioned wake:

- (1) Thickness has little effect on the amount of vorticity within the core at a given t^* (Figure 8).
- (2) Thickness has almost no effect on the size of the core at a given t (Figure 9).

- (3) Except in the very initial stages of roll-up, the core is of an approximately elliptic shape with height/wiith ratio about 0.8 for all three thickness ratios studied (Figure 10).
- The number of turns of the spiral within the core at a given t^* increases with reduction of ϵ , except for very small values of t^* when the spiral is, in any case, ill-defined (Figure 11). About one and three-quarter turns are observed for the $\epsilon = .04$ case at $t^* = .0128$ and for the $\epsilon = .05$ case at $t^* = .0160$, and for the $\epsilon = .06$ case at $t^* = .0192$, just over one and a half turns.
- that the original tip point of the unrolled wake does not become the tip point of the spiral; instead it recedes back along the outer edge of the coil. This appears to be true also for subsequent tip points of the spiral these do not remain at the tip but are dragged back along the outer edge of the spiral in their turn and their place is taken by other points which were originally more inboard along the upper edge of the unrolled wake.

7. FUTURE WORK

It is hoped to extend the present work into the more complete stages of the rolling-up and also to deal with different wake cross-sections and spanwise loadings.

For the later stages of the roll-up it would appear almost impossible to follow the spiral right into the center of the core and it is quite likely that considerable overlapping of elements may then occur there. Provided, however, that the outer winds of the spiral remain orderly and consistent, this need not trouble us, since what matters is the presence of the correct amount of vorticity in the core region, its precise location having little effect on the outer spiral. In effect we will be employing, automatically, the "condensing" procedure of Moore (4) wherebye the central part of the spiral is replaced by a point vortex.

Accuracy may, possibly, be improved by the use of curvilinear triangular elements instead of straight sided ones and also by use of a more sophisticated numerical integration method, such as the Runge-Kutta method.

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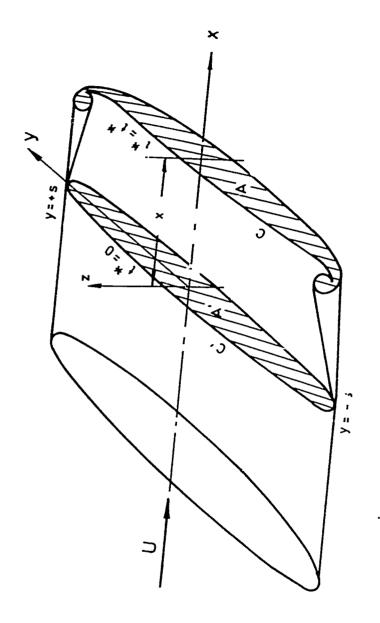


FIG.1 WAKE CROSS - SECTIONS & SYSTEM OF AXES.

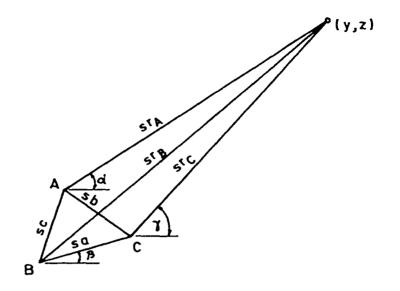


FIG. 2 NOTATION FOR A TRIANGULAR ELEMENT & A FIELD POINT

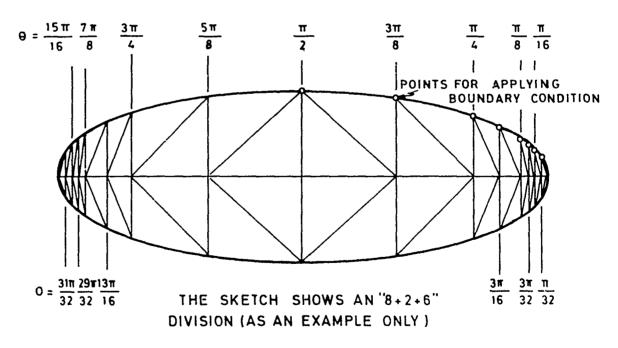
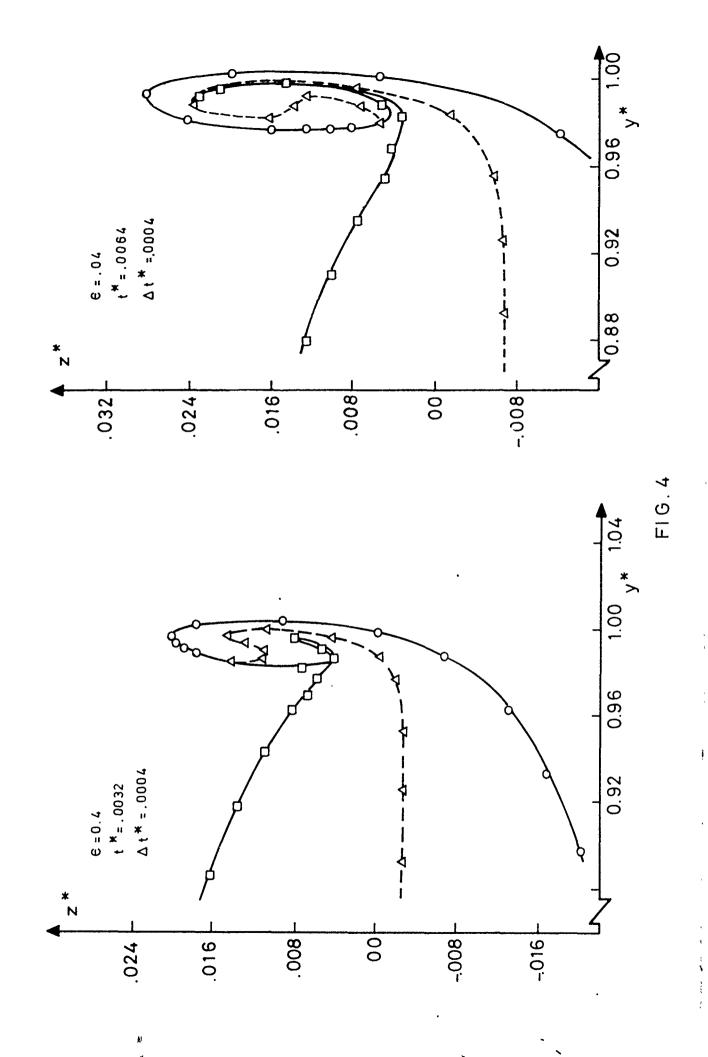


FIG. 3 LAYOUT OF ELEMENTS IN AN ELLIPTIC WAKE



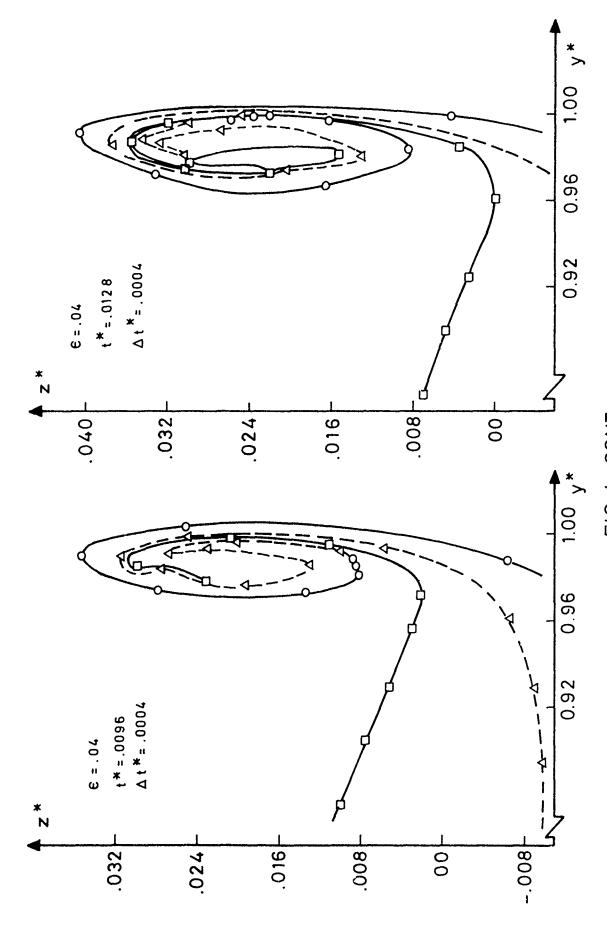
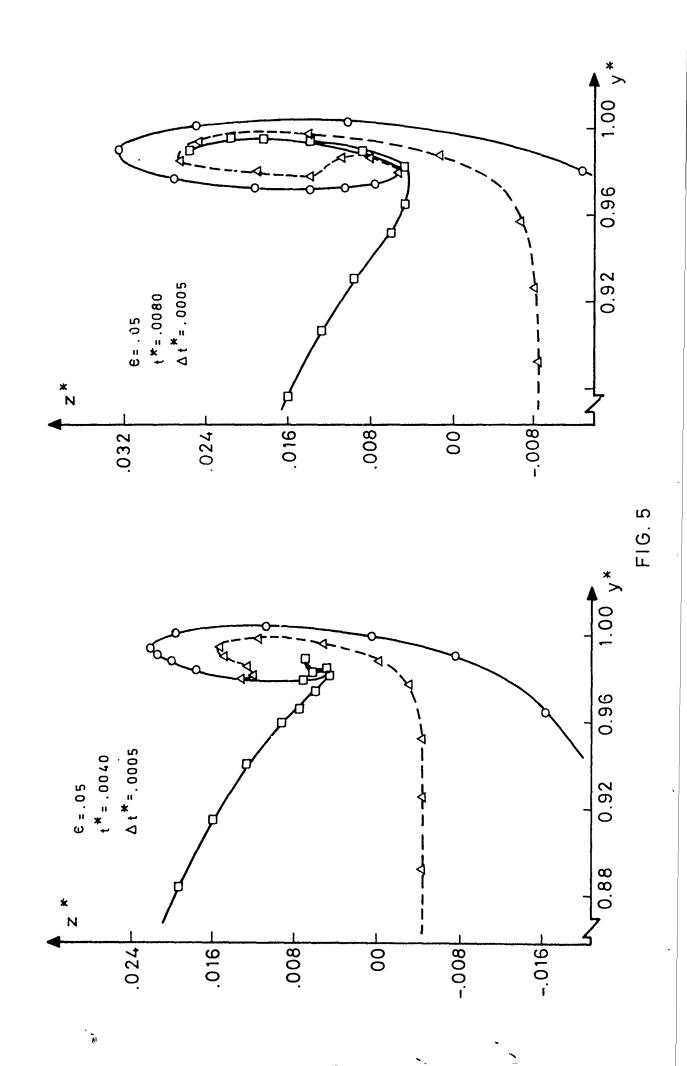


FIG.4 CONT.



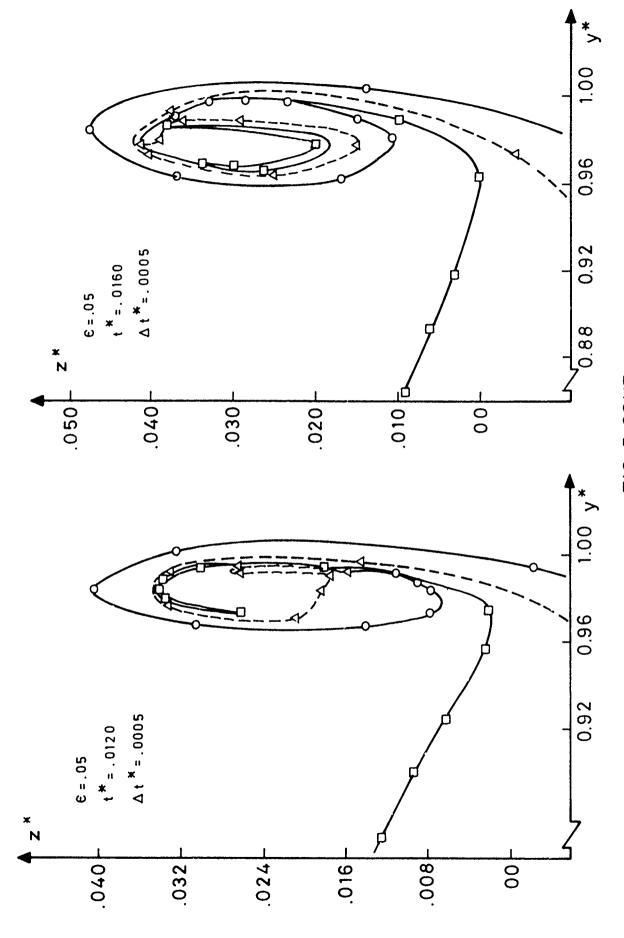
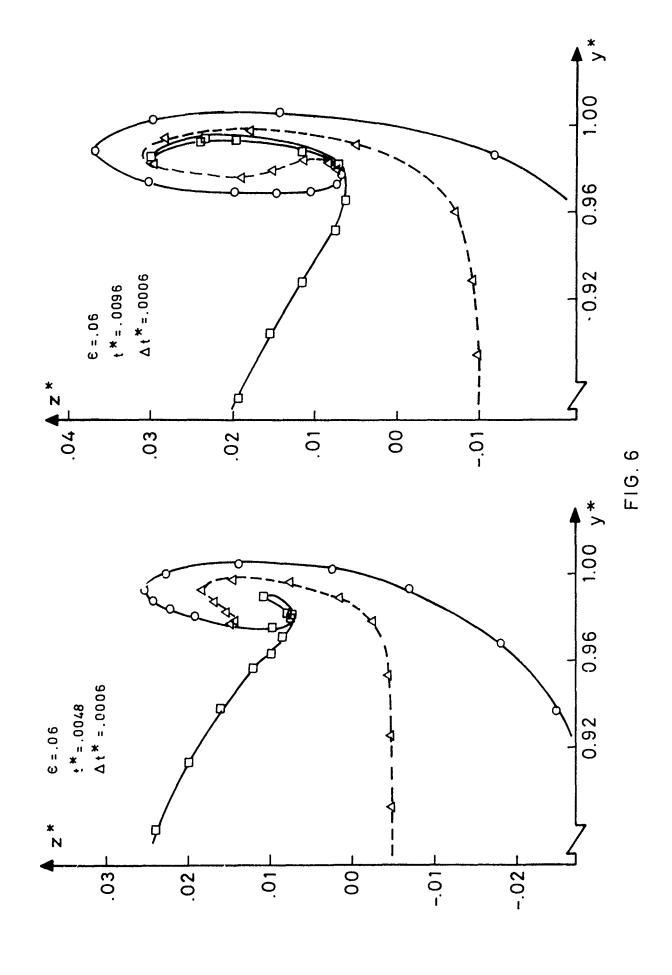


FIG. 5 CONT.



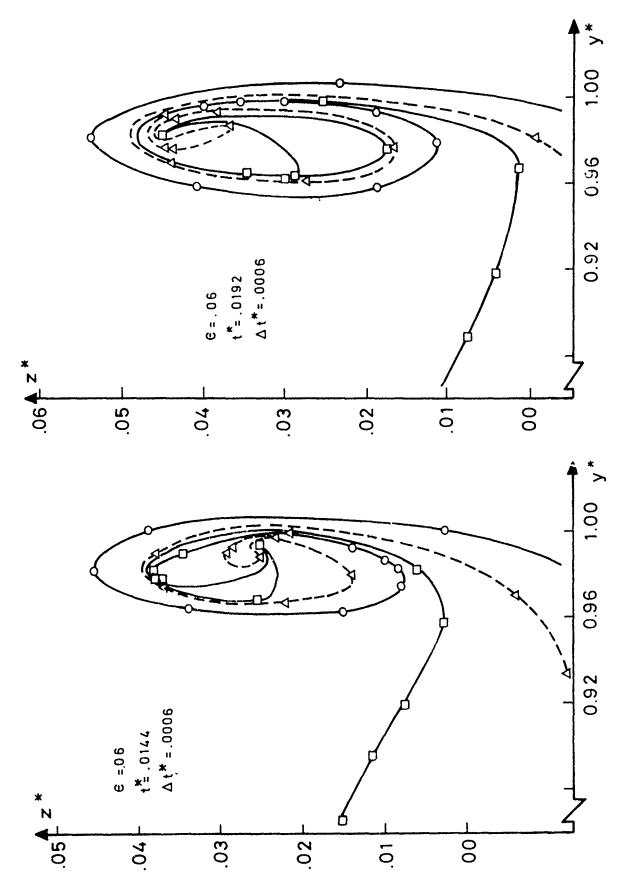


FIG. 6 CONT.

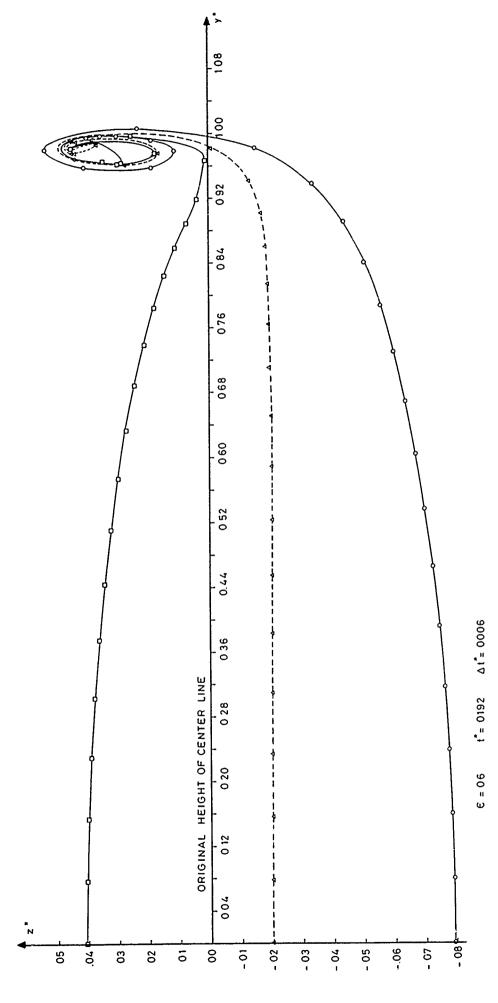
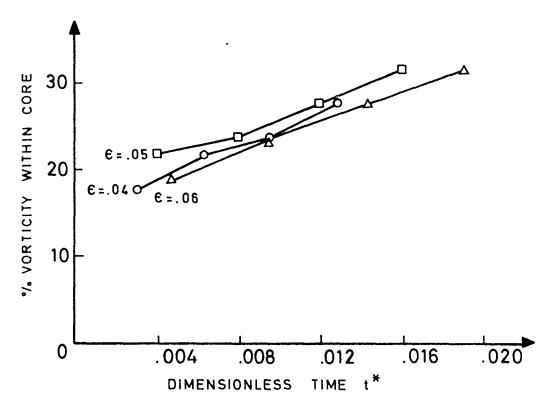
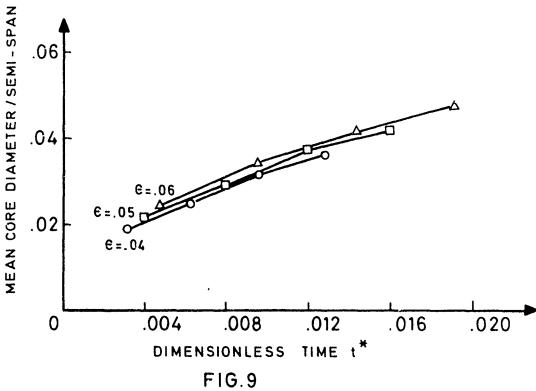
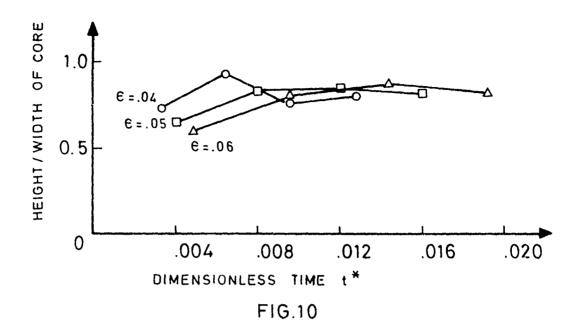


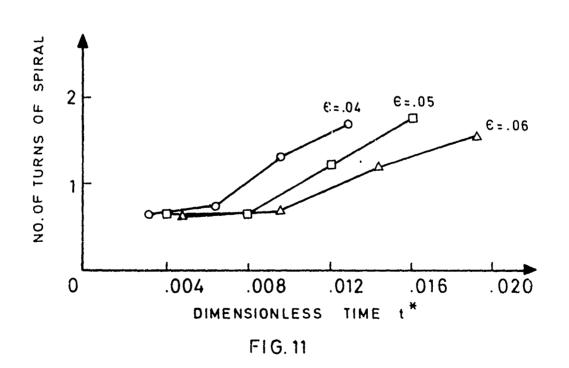
FIG 7 - EXAMPLE OF A COMPLETE HALF WAKE











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Previous investigations of wing-wake roll-up have	resigned the tasks to be a	
vortex sheet of zero thickness. This immediately	•	
as soon as the process starts, a spiral of mear ax		
finite number of turns, forms at the edges, as pred		
which must apply to the early stages of roll-up for	r any sheet of zero thickness,	
In addition, most investigators, starting with Wes		
continuous vortex sheet by discrete vortex lines. In this report, the afore-		
mentioned unrualistic features are removed by assur	ning that the wake	

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cross-section has a finite thickness and some plausible shape. A two-dimensional method, analogous to that of Westwater, is developed, assuming that the wake cross-section contains vorticity in an otherwise irrotational field. The wake is divided into triangular elements and the vorticity in these is determined by assuming a linear transverse velocity profile in the wake and that the initial, unroiled wake moves downwards as determined by the wing spanwise loading through ordinary wing-wake theory. Euler time-step integration is then used to calculate the wake development under its own induced velocity field, ignoring viscous dissipation. Three examples of the initial stages of roll-up, for elliptic wakes of thickness ratios .04 .05 and .06 are calculated. A finite spiral structure is observed to develop and, within the range covered, the thickness only seems to affect the number of turns in the spiral, other parameters seeming to be almost unaffected. Plans for continuation of the work are discussed.